

# Ampère Meetings

## Distributed Systems: A Scientific Outlook

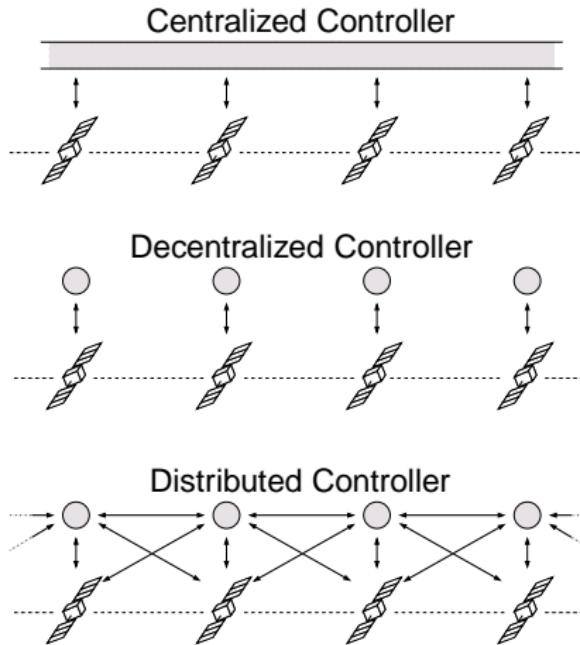
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2014

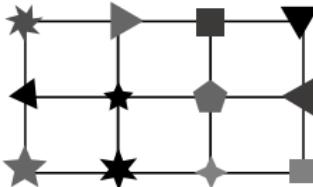
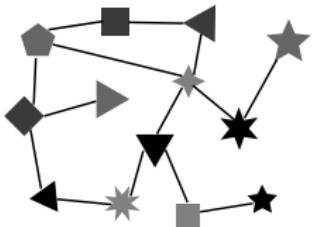


# Centralized / Distributed / Decentralized

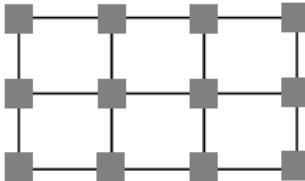
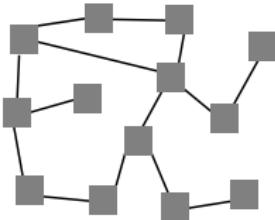


# A Classification of Distributed Systems

Heterogeneous



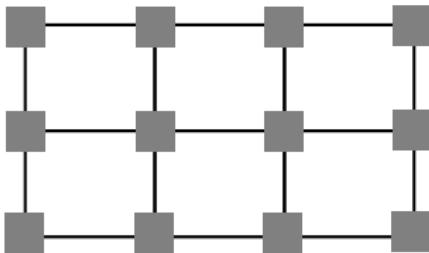
Homogeneous



Arbitrary interconnections

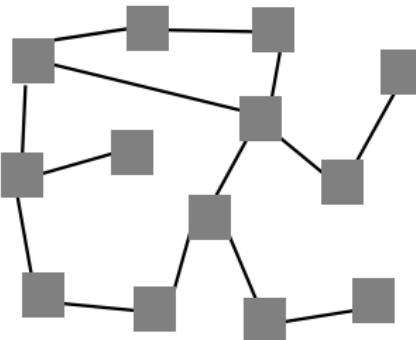
Regular lattice

# Homogeneous with Regular Lattice



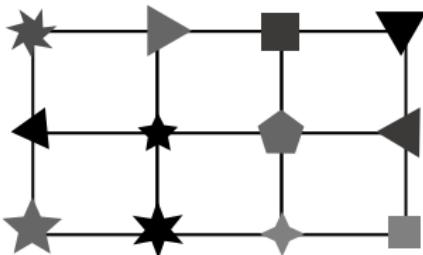
- B. Bamieh, M. Jovanovic, P. Mitra and S. Patterson "Effect of topological dimension on rigidity of vehicle formations: Fundamental limitations of local feedback." CDC 2008.
- B. Bamieh, F. Paganini and M.A. Dahleh. "Distributed control of spatially invariant systems." IEEE Transactions on Automatic Control 47(7):1091-1107, 2002.

# Homogeneous with Arbitrary Interconnections



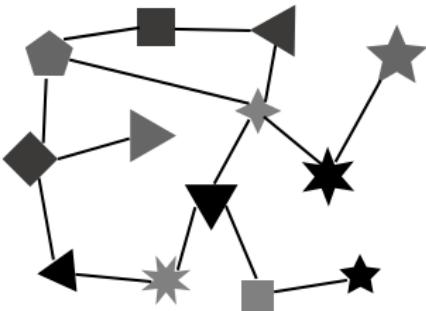
- A. Fax and R. Murray. "Information flow and cooperative control of vehicle formations." IEEE Transactions on Automatic Control 49(9):1465-1476, 2004.
- P. Massioni and M. Verhaegen. "Distributed control for identical dynamically coupled systems: A decomposition approach." IEEE Transactions on Automatic Control 54(1): 124-135, 2009.

# Heterogeneous with Regular Lattice



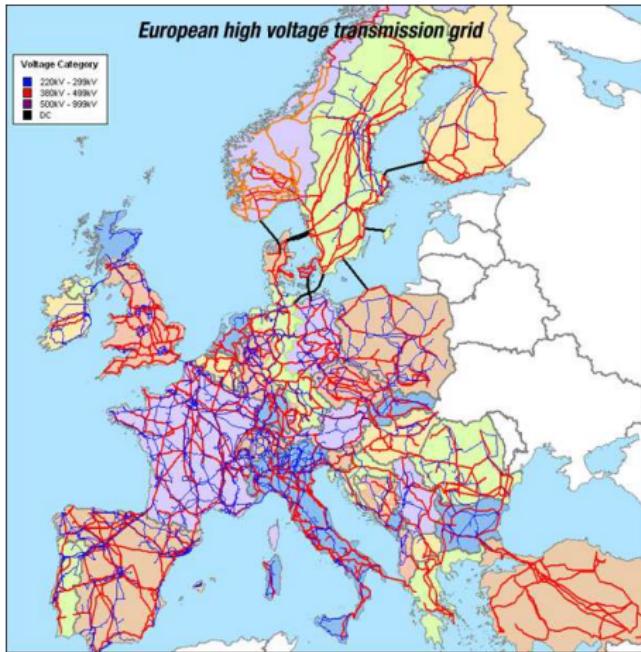
- G.E. Dullerud and R. D'Andrea. "Distributed control of heterogeneous systems." IEEE Transactions on Automatic Control, 49(12):2113-2128, 2004.
- J.K. Rice and M. Verhaegen. "Distributed control: A sequentially semi-separable approach for heterogeneous linear systems." IEEE Transactions on Automatic Control, 54(6):1270-1283, 2009.

# Heterogeneous with Arbitrary Interconnections



- C. Langbort, R.S. Chandra and R. D'Andrea. "Distributed control design for systems interconnected over an arbitrary graph." IEEE Transactions on Automatic Control, 49(9):1502-1519, 2004.

# Application: Electric Grid



# Applications: Adaptive Optics

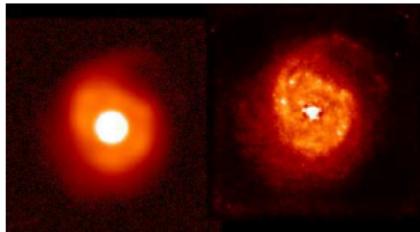
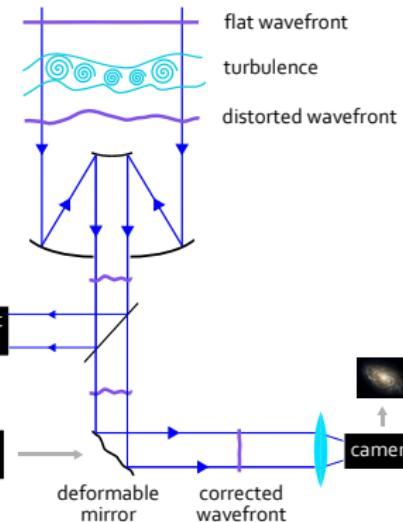


Image: Canada France Hawaii Telescope



Image: Yuri Beletsky, Paranal Observatory, Chili



# Application: Flow Control

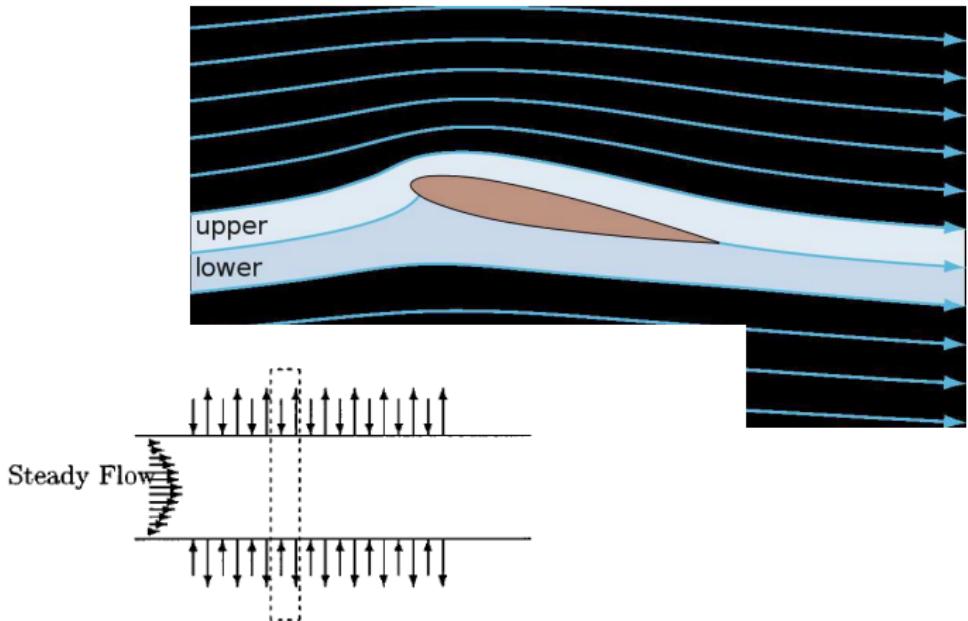


Fig. 3. 2-D Poiseuille flow with active boundary control.

# Applications: Multi-Agent Systems (?)

