

Conducted Interferences of Power Converters with Parametric Uncertainties in the Frequency Domain

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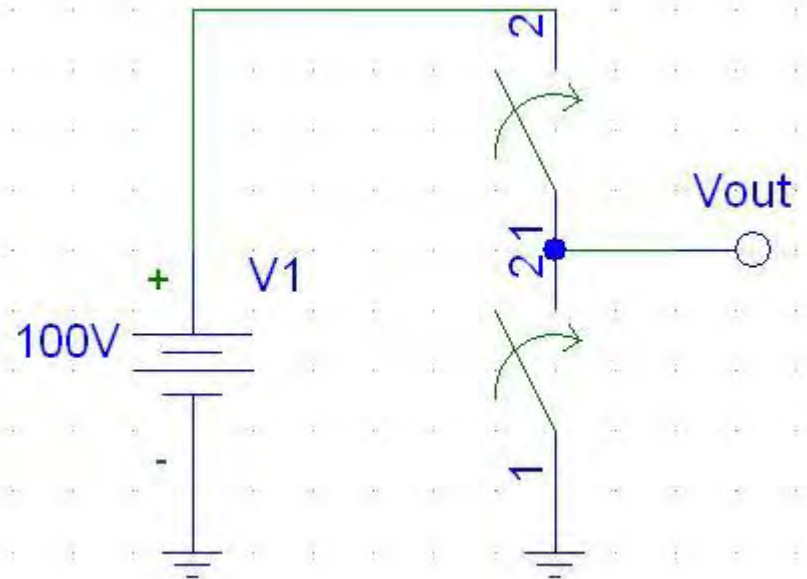
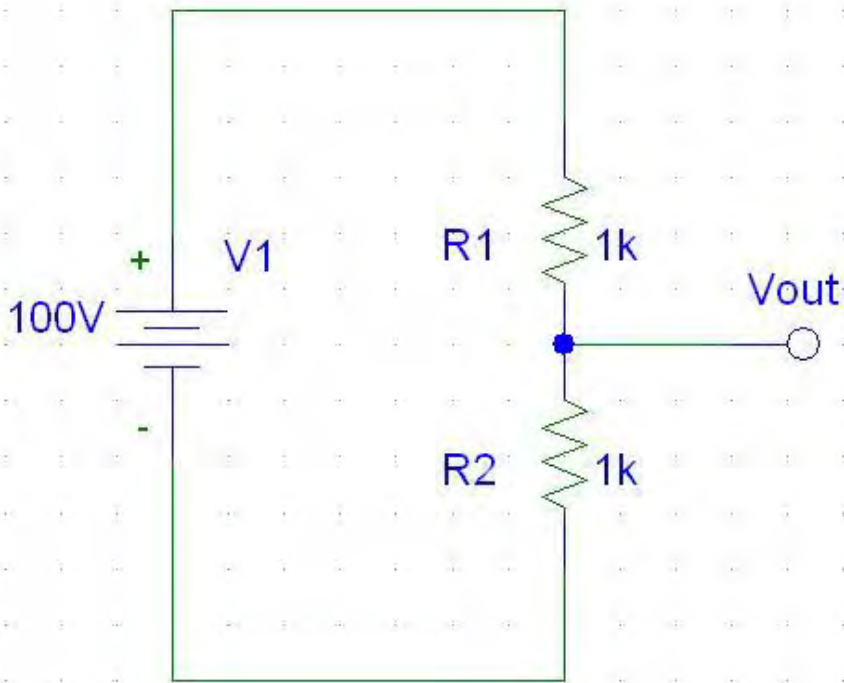


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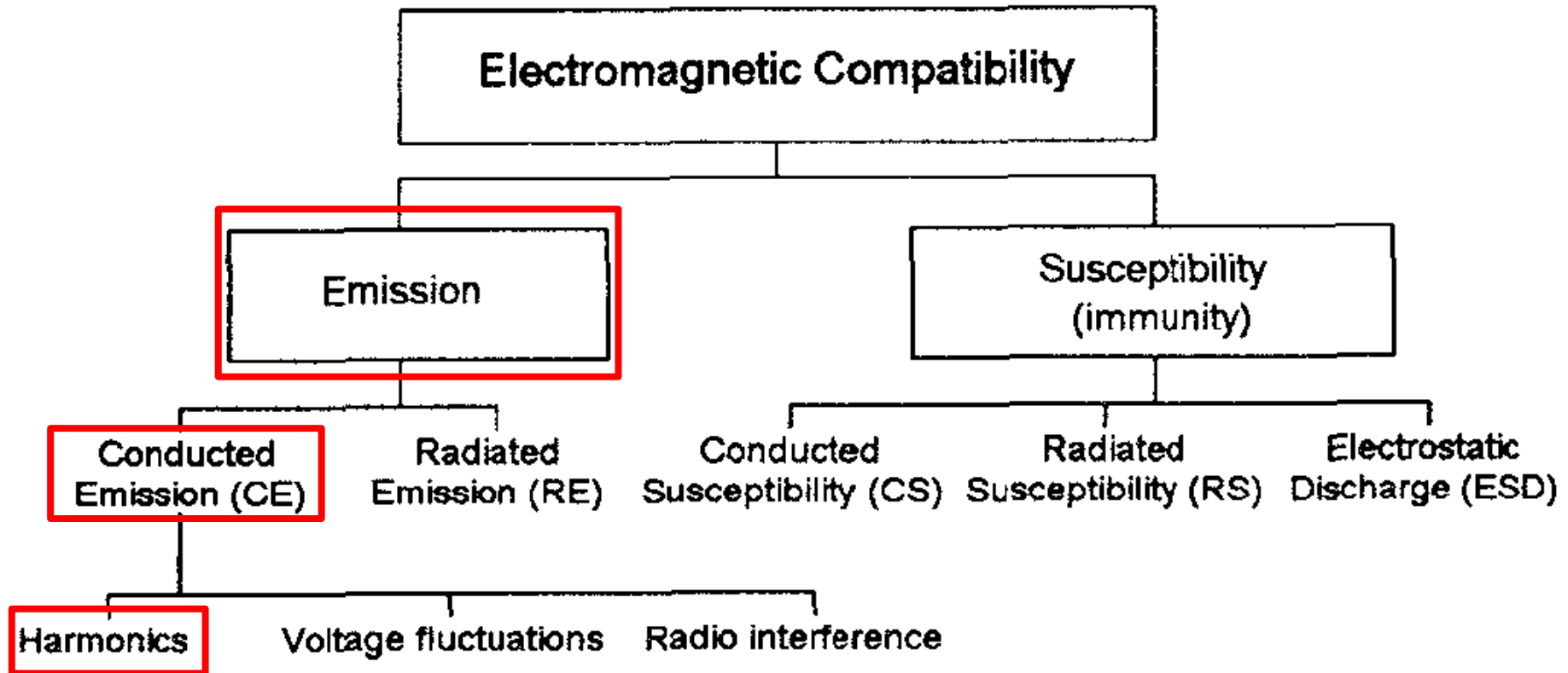
- ↪ Introduction
- ↪ What exists already
- ↪ What we propose
- ↪ Results
- ↪ Future research
- ↪ References
- ↪ Questions

Introduction

- Power Converter [1]

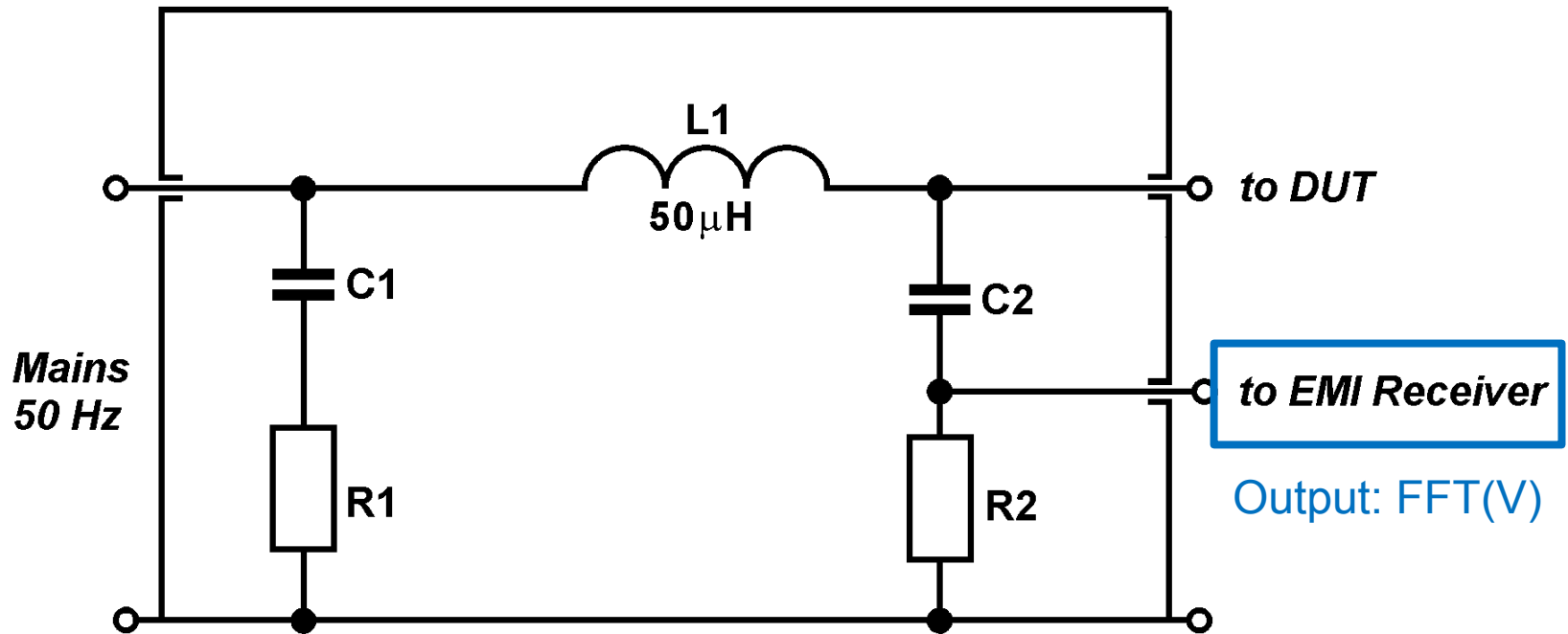


- Electromagnetic Compatibility [2]



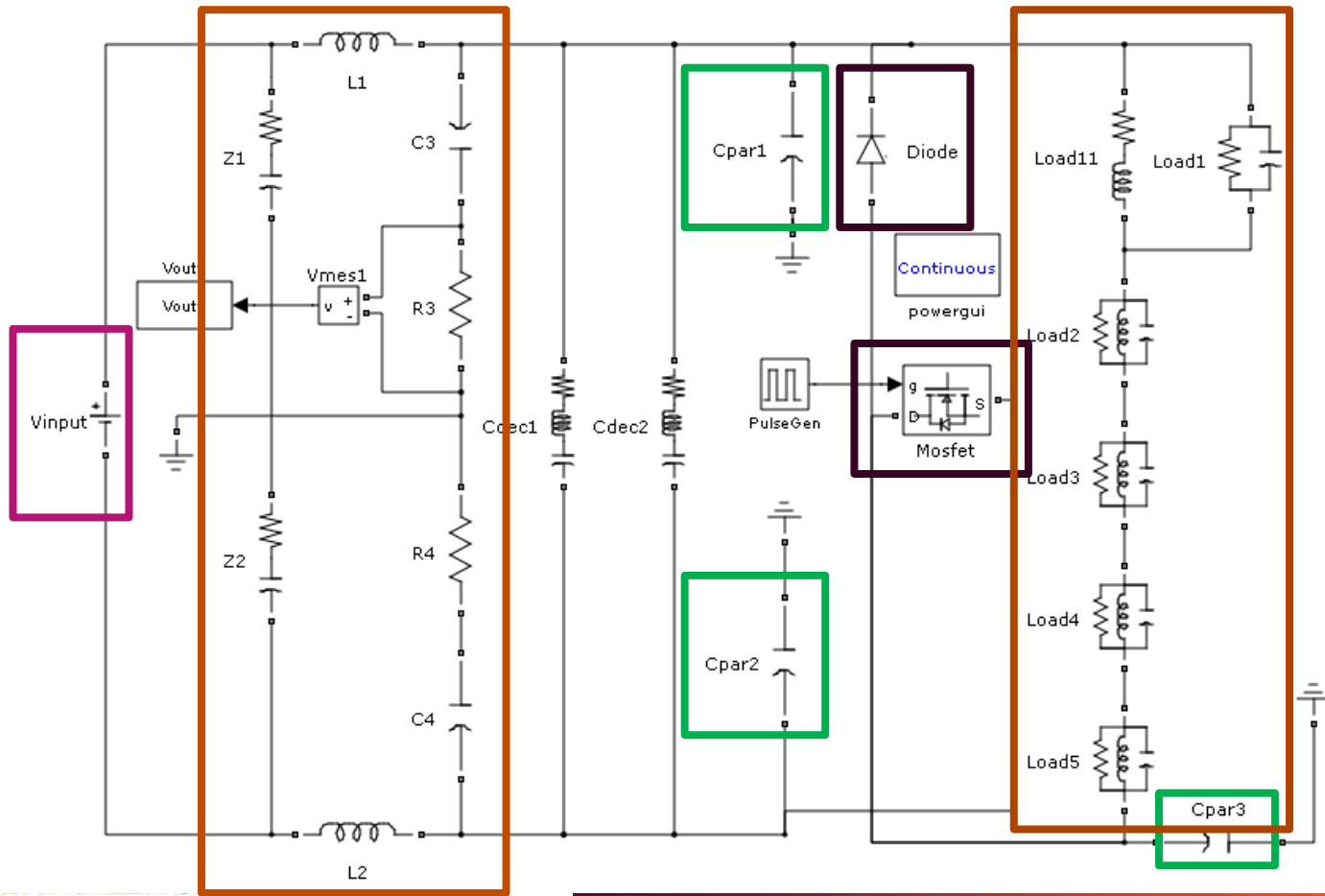
↳ LISN (Line Impedance Stabilization Network)

LISN 50 μH



- LISNs are multi-line low pass filter networks used for conducted emissions measurement. They are placed between the power mains and the EUT (Equipment Under Test) to stabilize line impedance, provide a 50 ohm RF connection, and eliminate unwanted RF signals from the line supply [3].

↪ Circuit Simulator (SimPower, SABER, SPICE, ...)



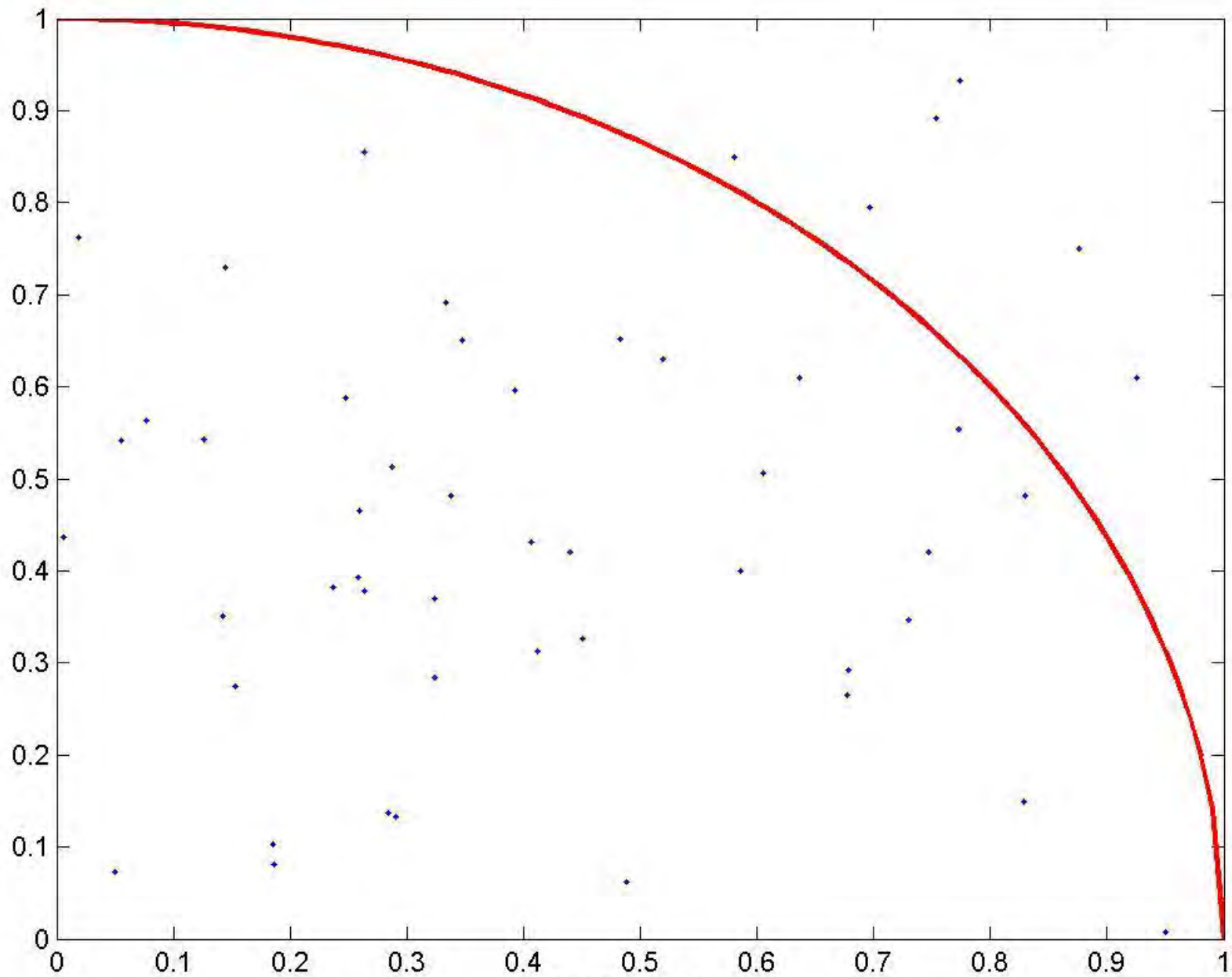
- ↪ Do we really know the exact values of the components?
- ↪ What about production dispersion?
- ↪ And ageing, temperature, humidity, etc. ?
- ↪ How do we take all these phenomena into account?

What exists already

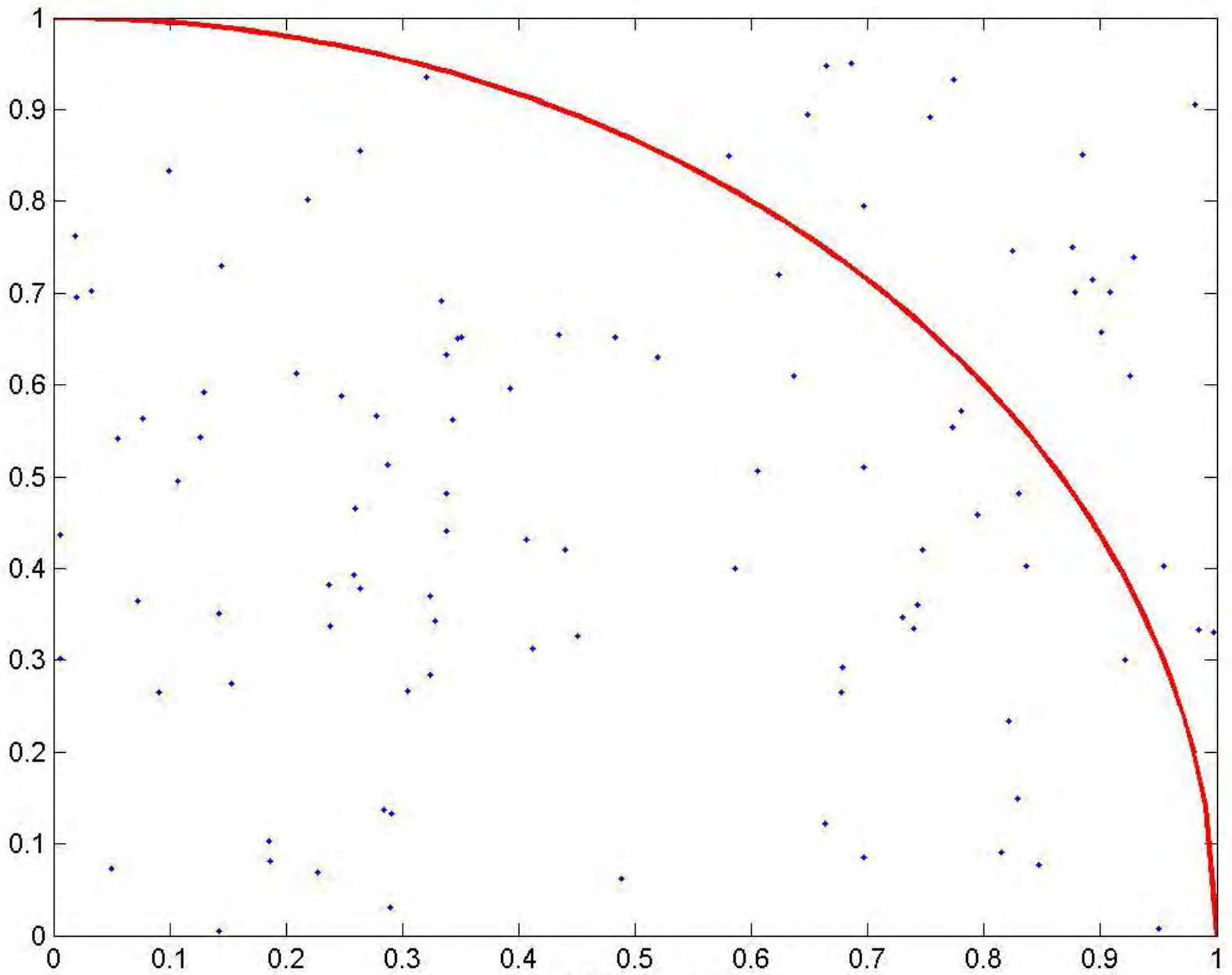


Monte Carlo Simulation

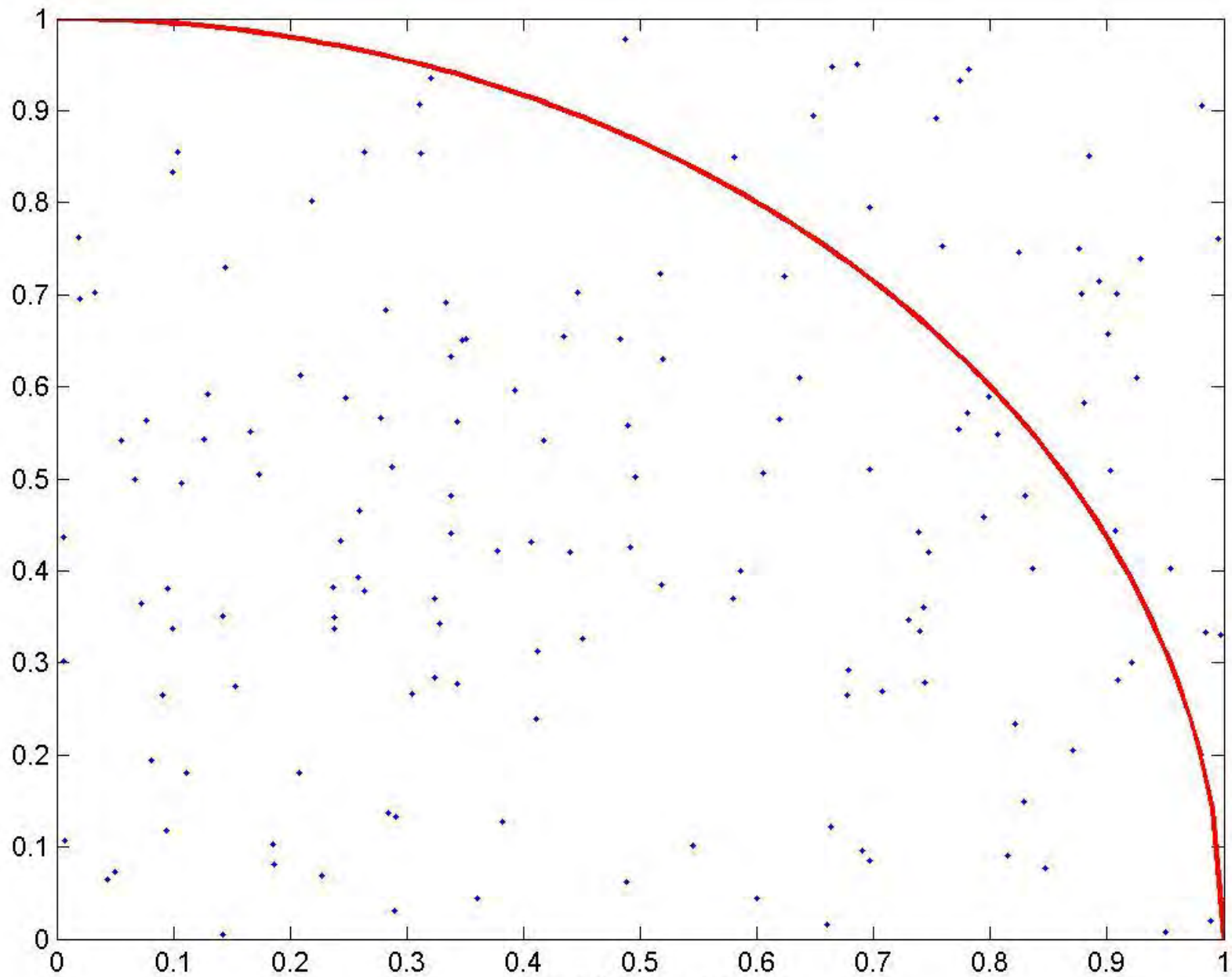
- Determine the Probability Density Function (PDF) of each unknown parameter.
- Generate many (10000 or more) sets of parameters following their PDFs.
- Solve the problem for all elements of the previous set.
- Estimate the output PDF (histogram or estimator).
- Estimation of the constant π using Monte Carlo (next)



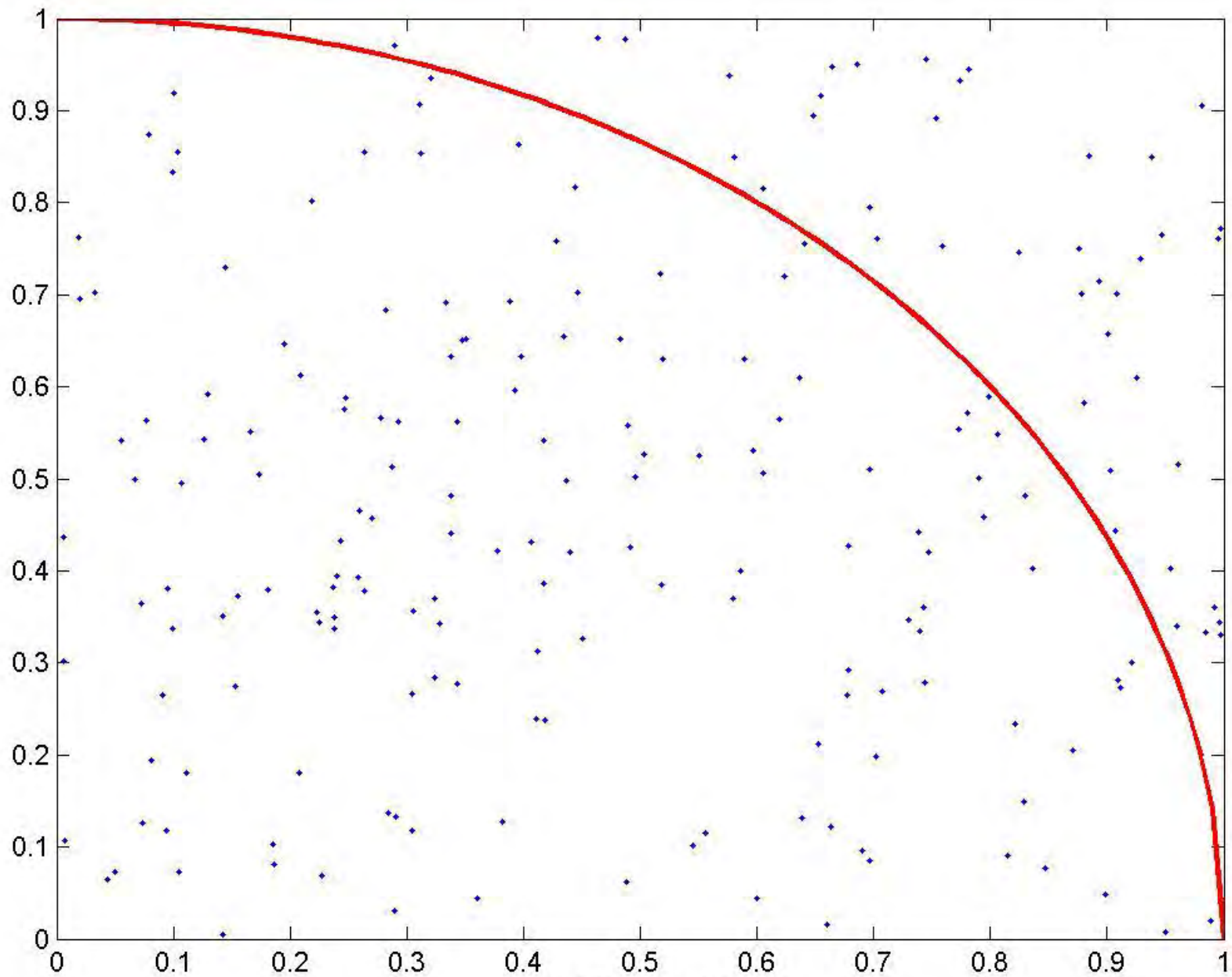
3.52 at 50 simulation.



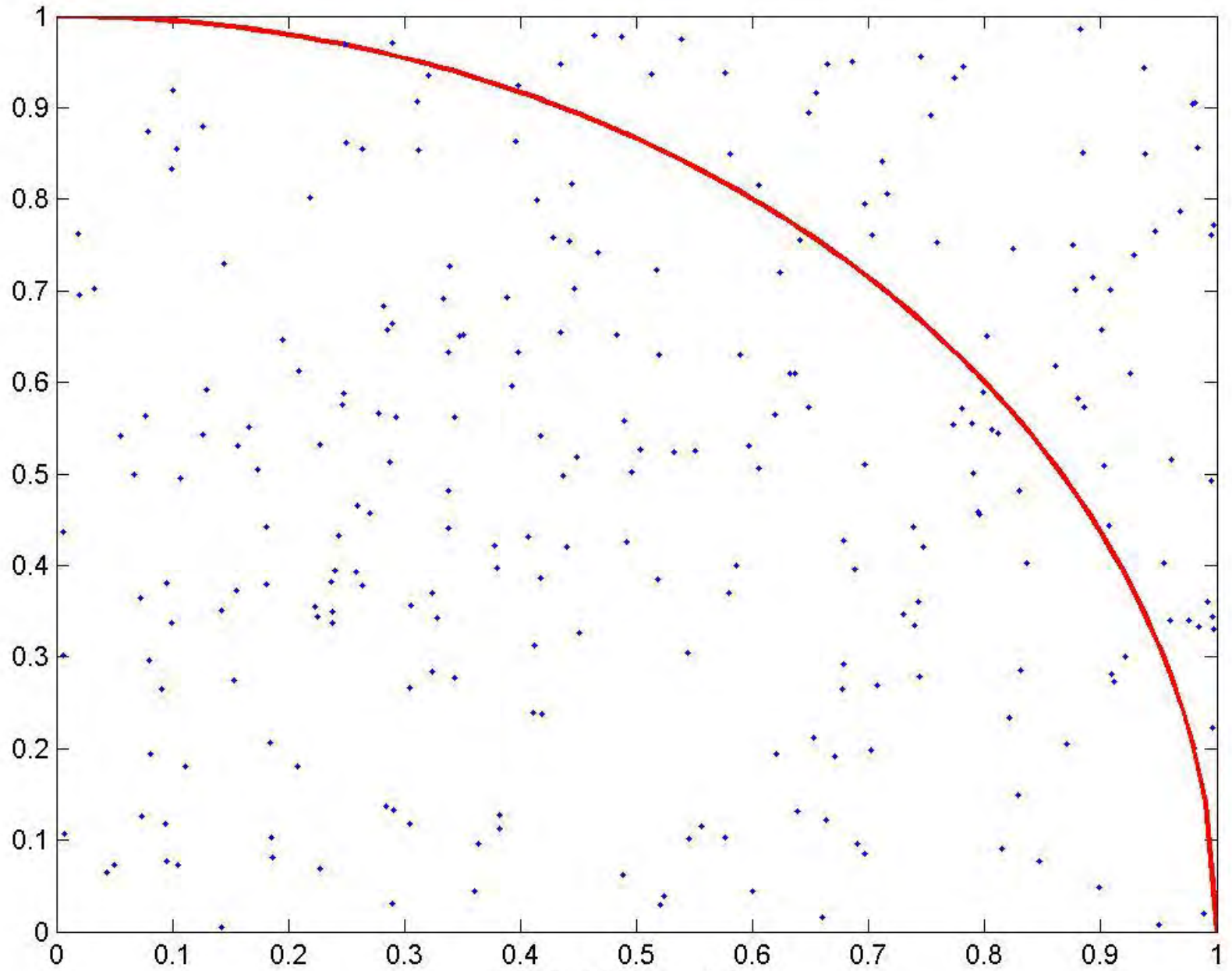
3.2 at 100 simulation.



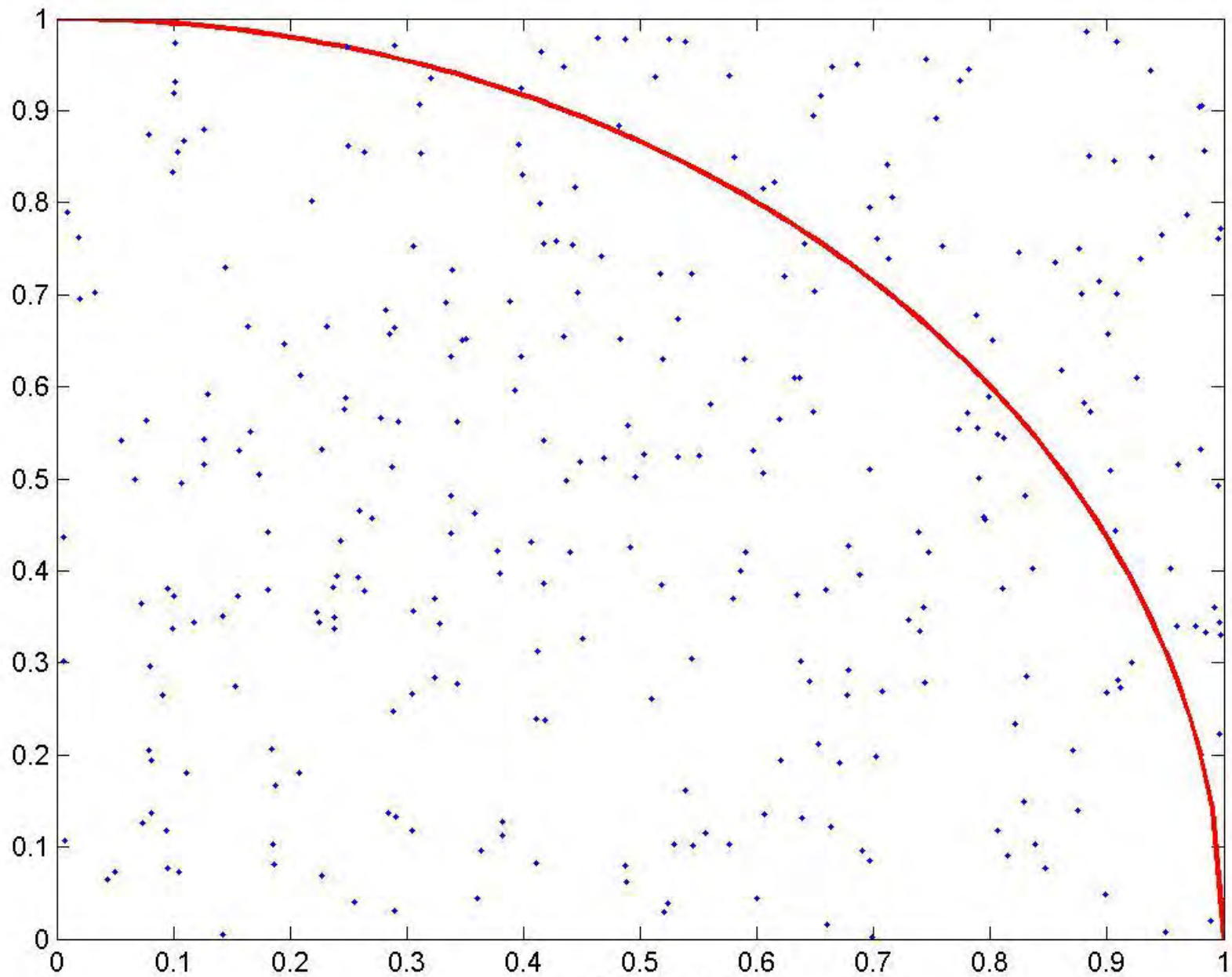
3.28 at 150 simulation.



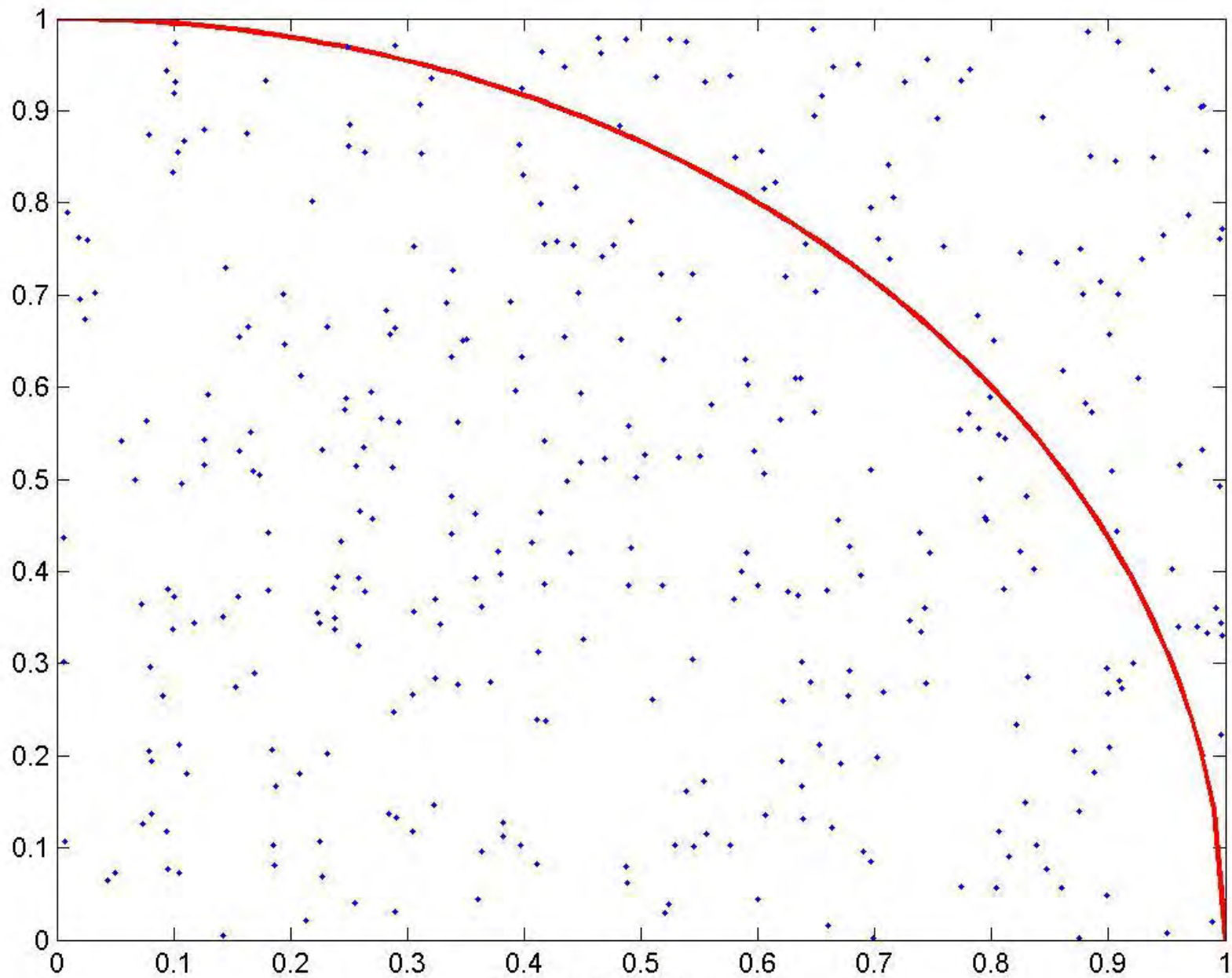
3.18 at 200 simulation.



3.056 at 250 simulation.



3.08 at 300 simulation.



3.1314 at 350 simulation.



Monte Carlo Simulation

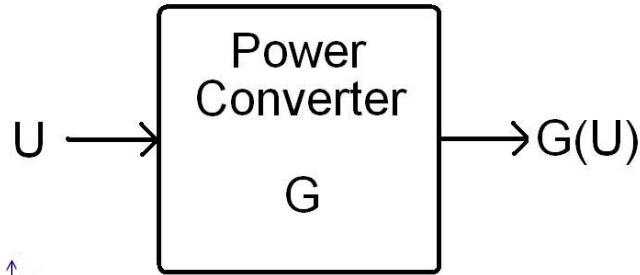
↪ **Advantages:** robust and easy to implement.

↪ **Disadvantages:** takes a LOT of time.

- ↪ Unscented Transform, Stroud, etc.
- ↪ Choose a few especific values of each parameter to simulate.
- ↪ Take a linear combination of the output to find the average and the variance.

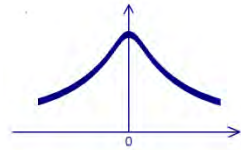
Unscented Transform [4]

Parameters
R, L, C, ...



Output
fft(V_{liss})

average



weights

ΔU

$$\bar{G} = E\{G(\bar{U} + \hat{u})\} = w_0 G(\bar{U}) + \sum_{i=1}^N w_i G(\bar{U} + S_i)$$

$$\sigma_G^2 = E\{(G(\bar{U} + \hat{u}) - \bar{G})^2\} = w_0 (G(\bar{U}) - \bar{G})^2 + \sum_{i=1}^N w_i (G(\bar{U} + S_i) - \bar{G})^2$$

Unscented Transform [4]

$$G(\bar{U} + \hat{u}) = G(\bar{U}) + \frac{dG}{du} \hat{u} + \frac{1}{2!} \frac{d^2 G}{du^2} \hat{u}^2 + \frac{1}{3!} \frac{d^3 G}{du^3} \hat{u}^3 + \dots$$

$$w_0 = 1 - \sum_i w_i$$

$$\sum_i w_i S_i^k = E\{\hat{u}^k\}$$

Order	Normalized Sigma Points and Weights		
	Weights	Sigma Points	Probability Distribution
1	0.500 0.500	-0.577 0.577	$w(\hat{u}) = \begin{cases} \frac{1}{2} & \hat{u} < 1 \\ 0 & \hat{u} > 1 \end{cases}$
2	0.278 0.444 0.278	-0.775 0 0.775	
4	0.119 0.239 0.284 0.239 0.119	-0.906 -0.538 0 0.538 0.906	
1	0.500 0.500	-1 1	$w(\hat{u}) = \frac{1}{\sqrt{2\pi}} e^{-\frac{\hat{u}^2}{2}}$
2	0.167 0.666 0.167	-1.73 0 1.73	
4	0.011 0.222 0.534 0.222 0.011	-2.857 -1.356 0 1.356 2.857	

Unscented Transform [4]

Table 1: Minimum number of sigma points for the second and fourth orders approximation

n_{RV}	N_{eq} (second order)	N_s (second order)	N_{eq} (fourth order)	N_s (fourth order)
1	4	2 + 1	8	4 + 1
2	14	5 + 1	43	15 + 1
3	34	9 + 1	155	39 + 1
4	69	14 + 1	449	90 + 1
5	125	21 + 1	1121	187 + 1
6	209	30 + 1	2507	359 + 1
7	329	42 + 1	5147	644 + 1
8	494	55 + 1	9866	1097 + 1
9	714	72 + 1	16 874	1788 + 1
10	1000	91 + 1	30 887	2807 + 1

Table 2: Comparison between minimum sigma point numbers and the general set

Number of RVs	Minimum number of sigma points	Number of sigma points with set	Weight	
			1	2
1	2 + 1	4 + 1	1/18	1/9
2	5 + 1	8 + 1	1/16	1/16
3	9 + 1	14 + 1	9/200	1/25
4	14 + 1	24 + 1	1/36	1/36
5	21 + 1	42 + 1	25/1568	1/49
6	30 + 1	76 + 1	9/1024	1/64
7	42 + 1	142 + 1	49/10368	1/81
8	55 + 1	272 + 1	1/400	1/100
9	72 + 1	530 + 1	121/61962	1/121
10	91 + 1	1044 + 1	1/1024	1/144

↪ **Advantages:** very fast.

↪ **Disadvantages:**

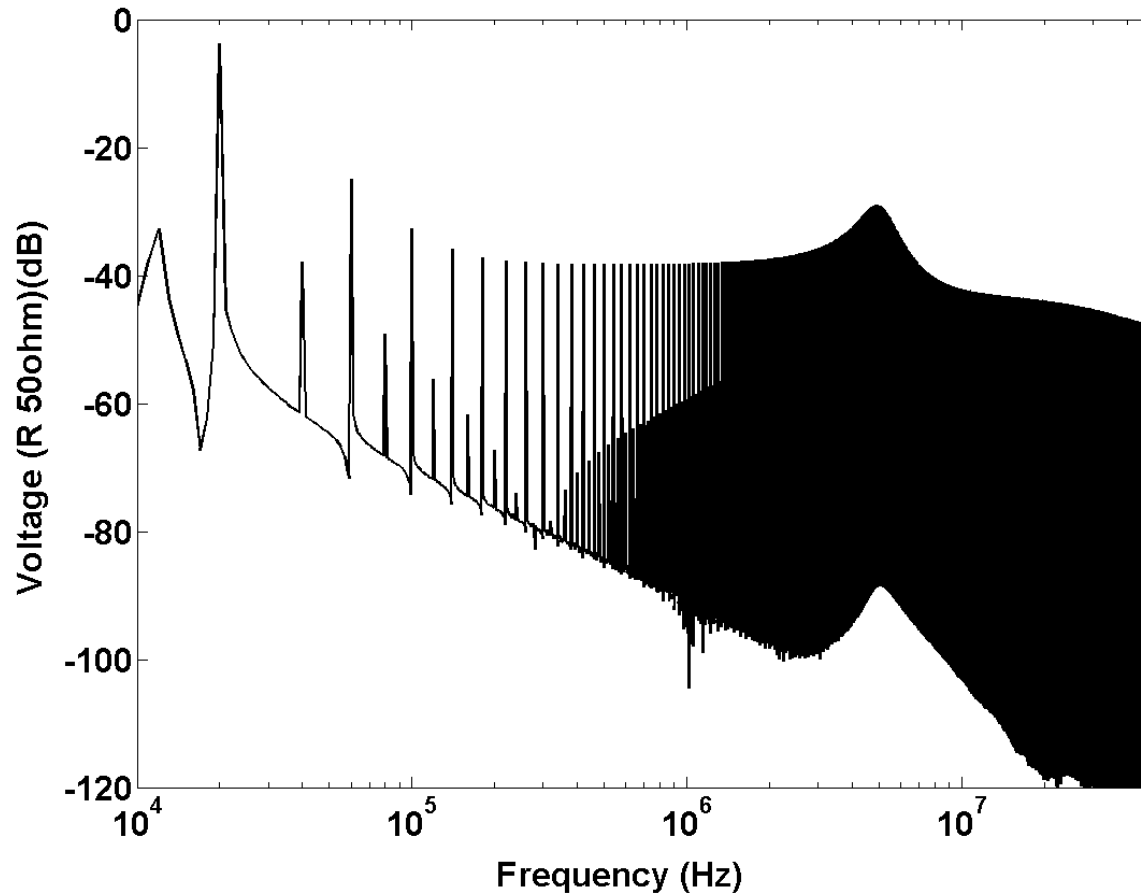
- the result is a variance or other higher statistical moments, but not the PDF itself.
- Can't guarantee precision (Taylor series).
- Becomes slow with large number of unknown parameters.

What we propose

What we propose

- We propose a methodology composed of the following steps:
- Output Reduction
- Sensitivity Analysis
- Model Reduction
- Transformation of Random Variables

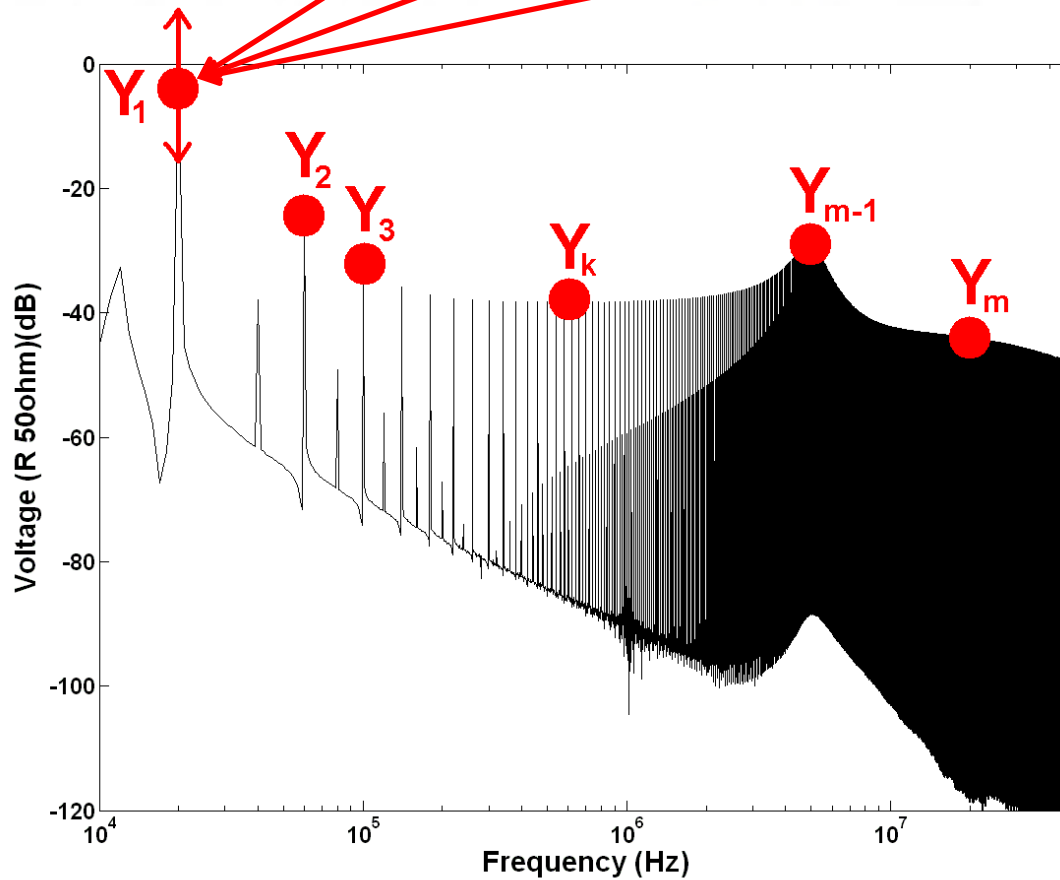
Output Reduction



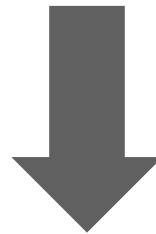
$$\tilde{f} = (f_1, f_2, \dots, f_m) \quad \mathcal{G} \quad Y_k = G_k(X_1, X_2, \dots, X_n) = G_k(\mathbf{X})$$

Sensitivity Analysis

$$Y_k = G_k(X_1, X_2, \dots, X_n) = G_k(X)$$



$$Y_k = G_k(X_1, X_2, X_3, X_4, X_5, X_6, \dots, X_n) = G_k(\mathbf{X})$$



$$\widetilde{Y}_k = \widetilde{G}_k(X_1, X_4, X_6) = \widetilde{G}_k(\widetilde{\mathbf{X}})$$

$\mathbf{X} = (X_1, X_2, \dots, X_n)$ multivariate continuous, $\mathbf{Y} = (Y_1, Y_2, \dots, Y_n) = \mathbf{g}(\mathbf{X})$. \mathbf{g} is one-to-one, so that its inverse exists and is denoted by

$$\mathbf{x} = \mathbf{g}^{-1}(\mathbf{y}) = \mathbf{w}(\mathbf{y}) = (w_1(\mathbf{y}), w_2(\mathbf{y}), \dots, w_n(\mathbf{y})).$$

Assume \mathbf{w} have continuous partial derivatives, and let

$$J = \begin{vmatrix} \frac{\partial w_1(\mathbf{y})}{\partial y_1} & \frac{\partial w_1(\mathbf{y})}{\partial y_2} & \dots & \frac{\partial w_1(\mathbf{y})}{\partial y_n} \\ \frac{\partial w_2(\mathbf{y})}{\partial y_1} & \frac{\partial w_2(\mathbf{y})}{\partial y_2} & \dots & \frac{\partial w_2(\mathbf{y})}{\partial y_n} \\ \vdots & \vdots & \dots & \vdots \\ \frac{\partial w_n(\mathbf{y})}{\partial y_1} & \frac{\partial w_n(\mathbf{y})}{\partial y_2} & \dots & \frac{\partial w_n(\mathbf{y})}{\partial y_n} \end{vmatrix}$$

Then

$$f_{\mathbf{Y}}(\mathbf{y}) = f_{\mathbf{X}}(\mathbf{g}^{-1}(\mathbf{y}))|J|.$$

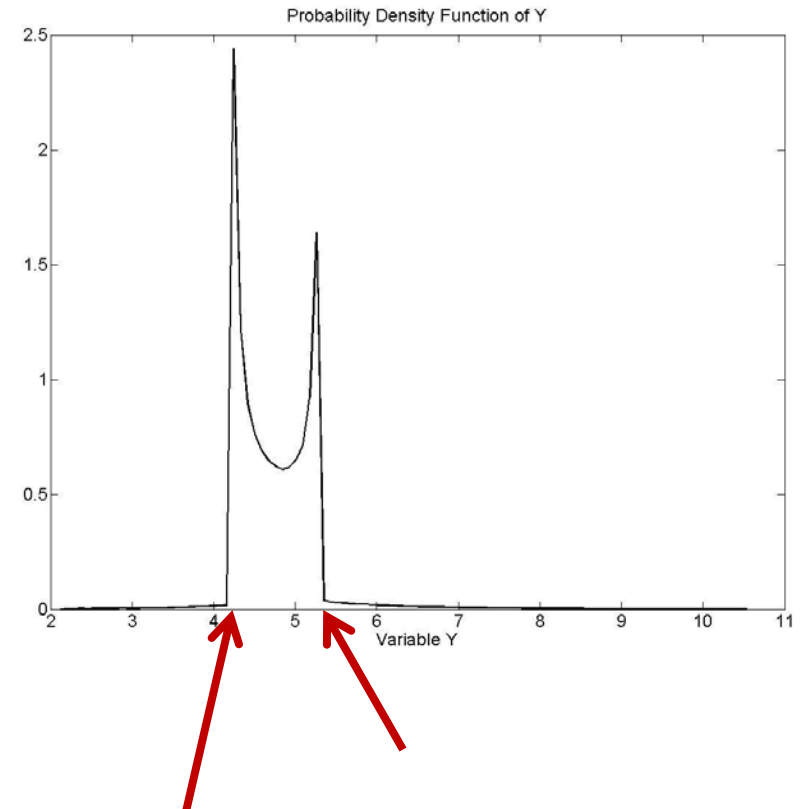
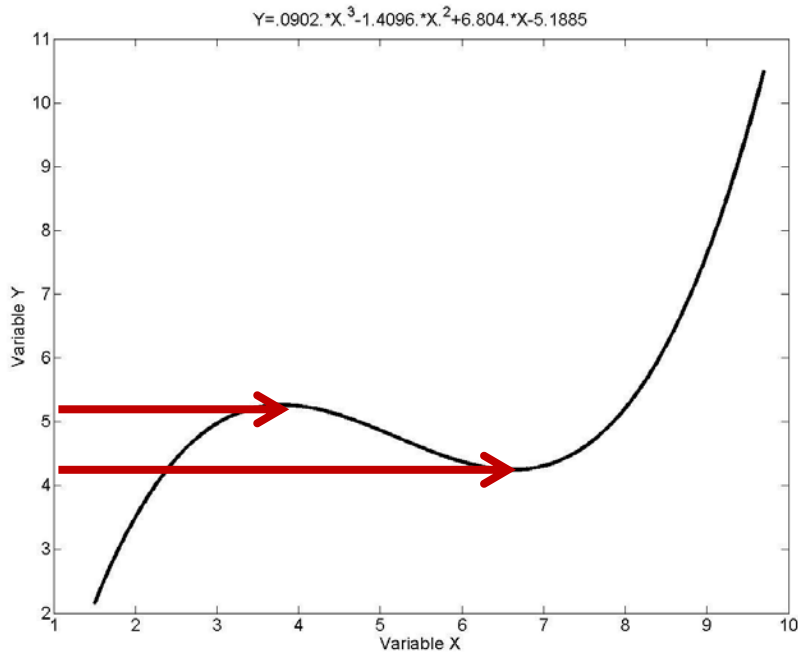
for \mathbf{y} s.t. $\mathbf{y} = \mathbf{g}(\mathbf{x})$ for some \mathbf{x} , and $f_{\mathbf{Y}}(\mathbf{y}) = 0$, otherwise.

Let Y be a function of the random variables X_1, X_2, \dots, X_n .

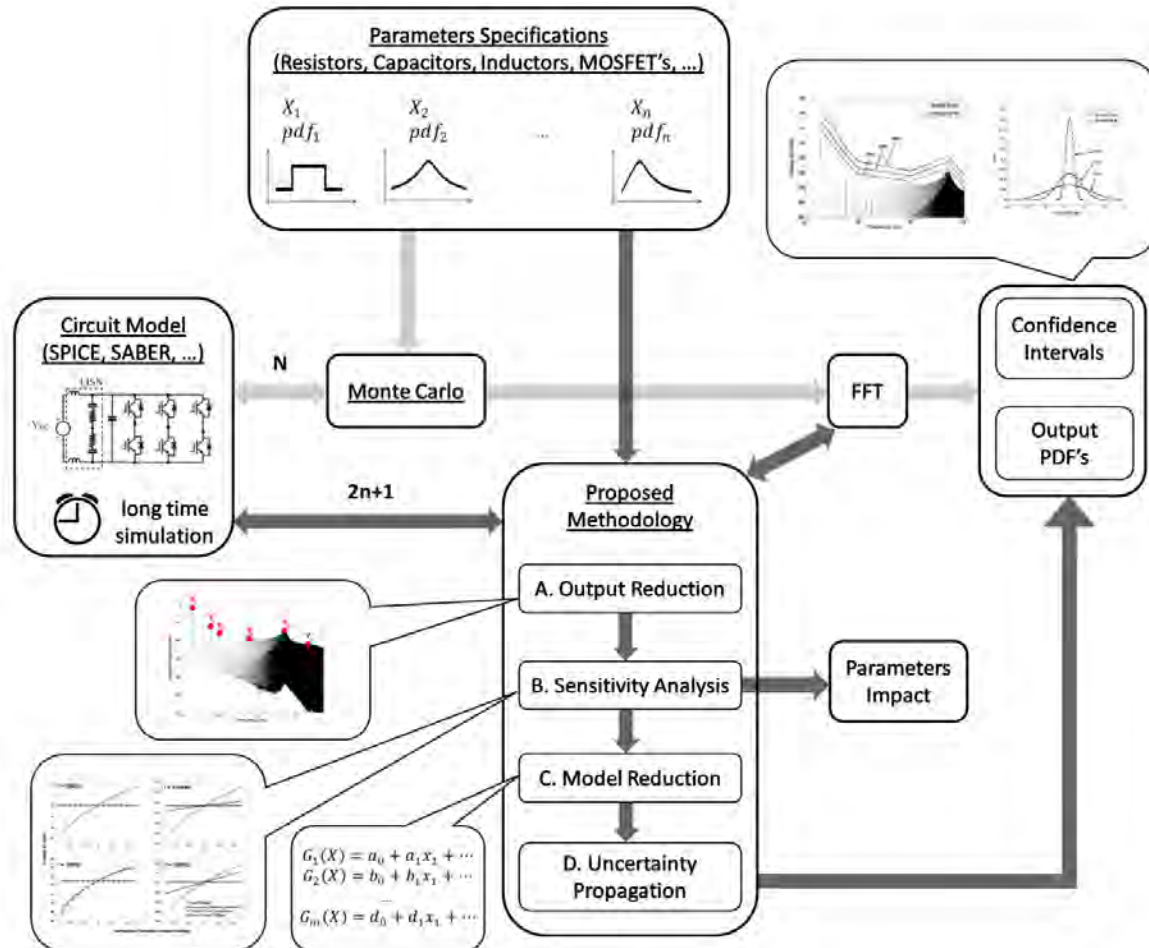
1. Find the region $Y \leq y$ in the (x_1, x_2, \dots, x_n) space.
2. Find $F_Y(y) = P(Y \leq y)$ by summing the joint pmf or integrating the joint pdf of X_1, X_2, \dots, X_n over the region $Y \leq y$.
3. (for continuous case) Find the pdf of Y by differentiating $F_Y(y)$, i.e., $f_Y(y) = \frac{d}{dy}F_Y(y)$.

Note. It can be generalized to multivariate $\mathbf{Y} = (Y_1, Y_2, \dots, Y_m)$.

Transformation of R. Variables [5]

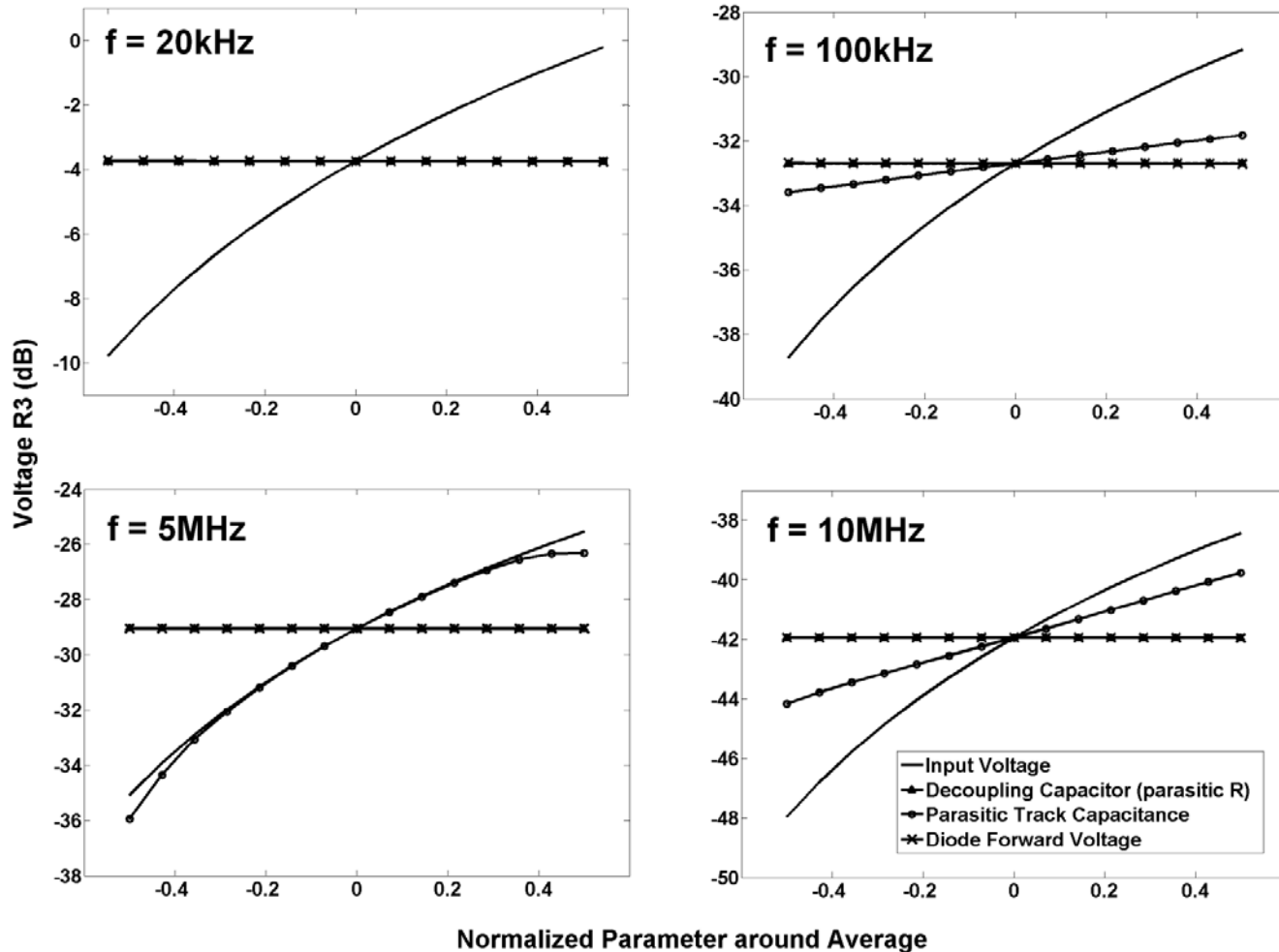


Overview

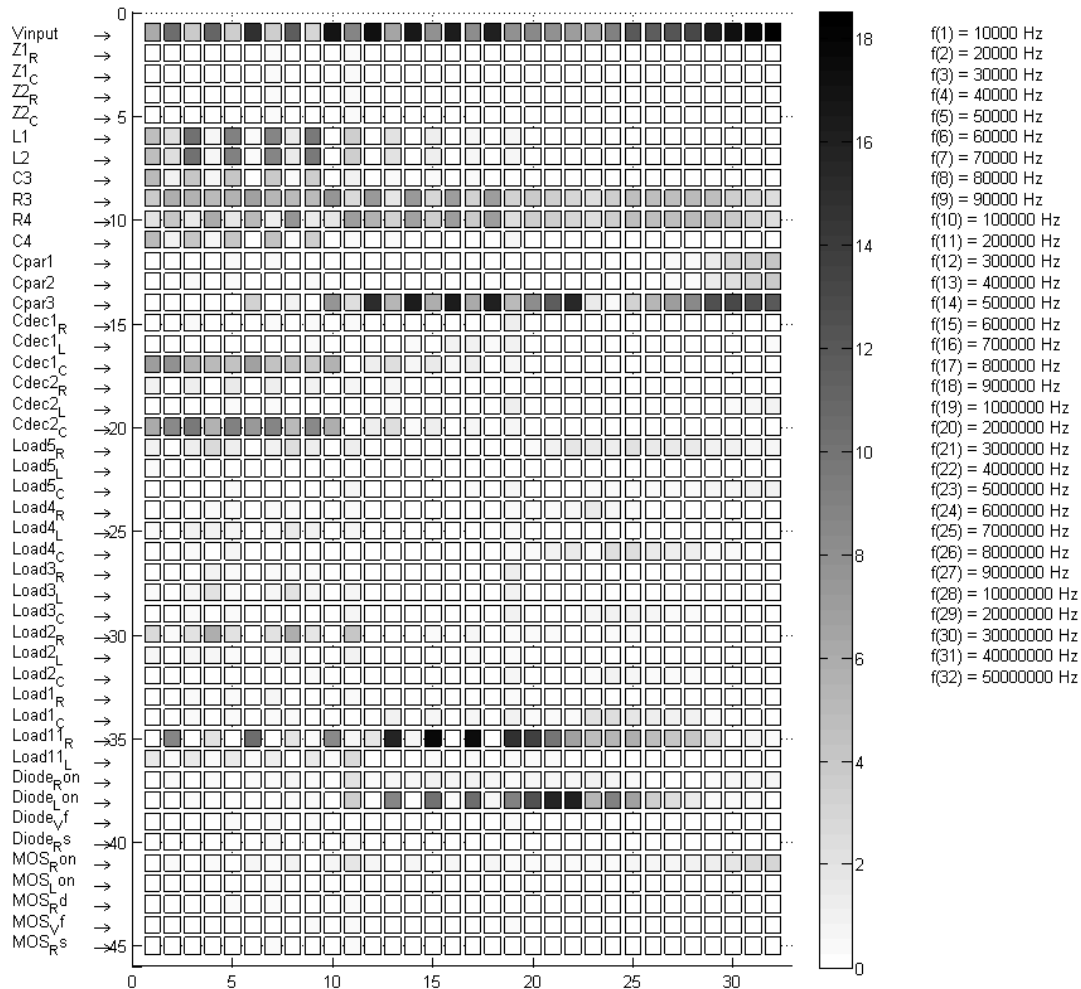


Results

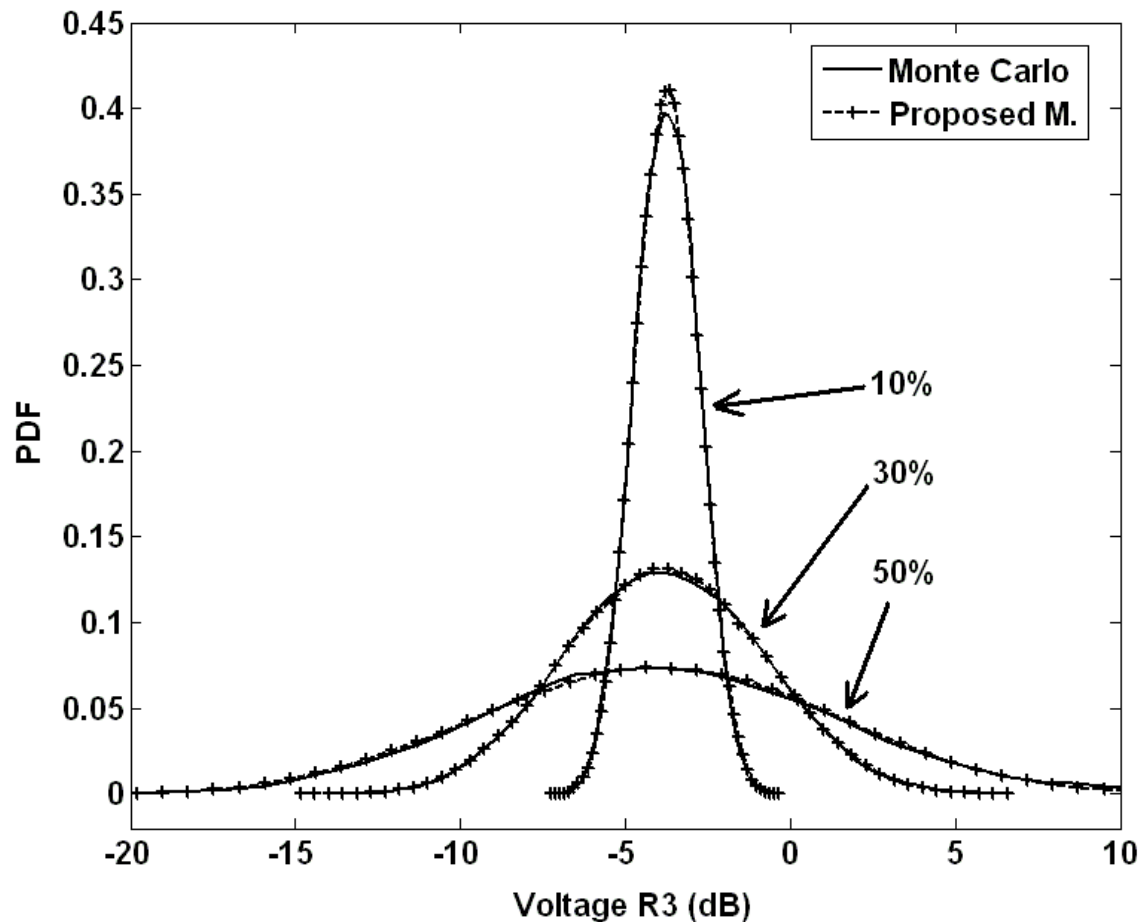
Results – Sensitivity Analysis



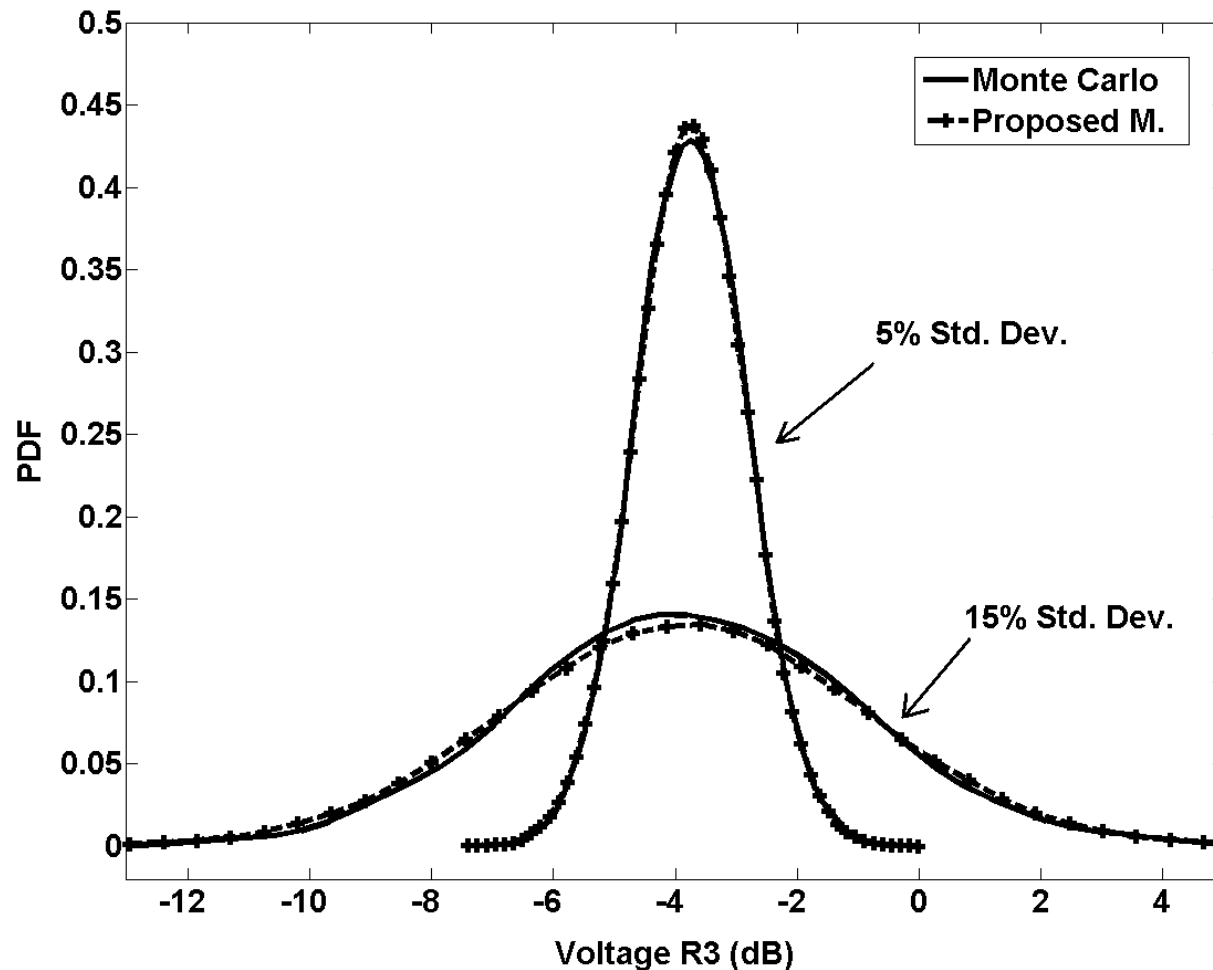
Results – Impact of Variables



Results – Output PDFs (normal input) @20kHz

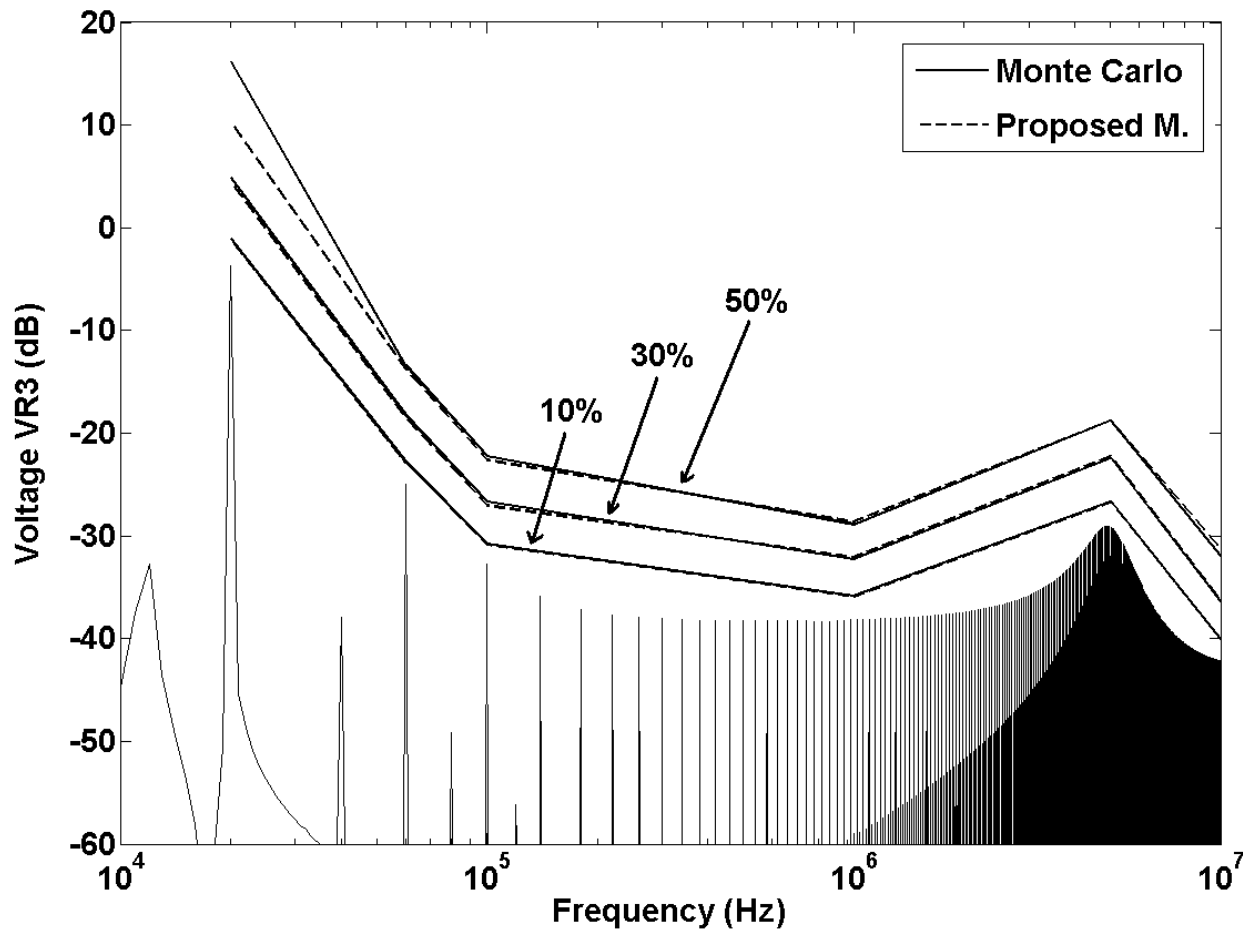


Results – Output PDFs (uniform input) @20kHz



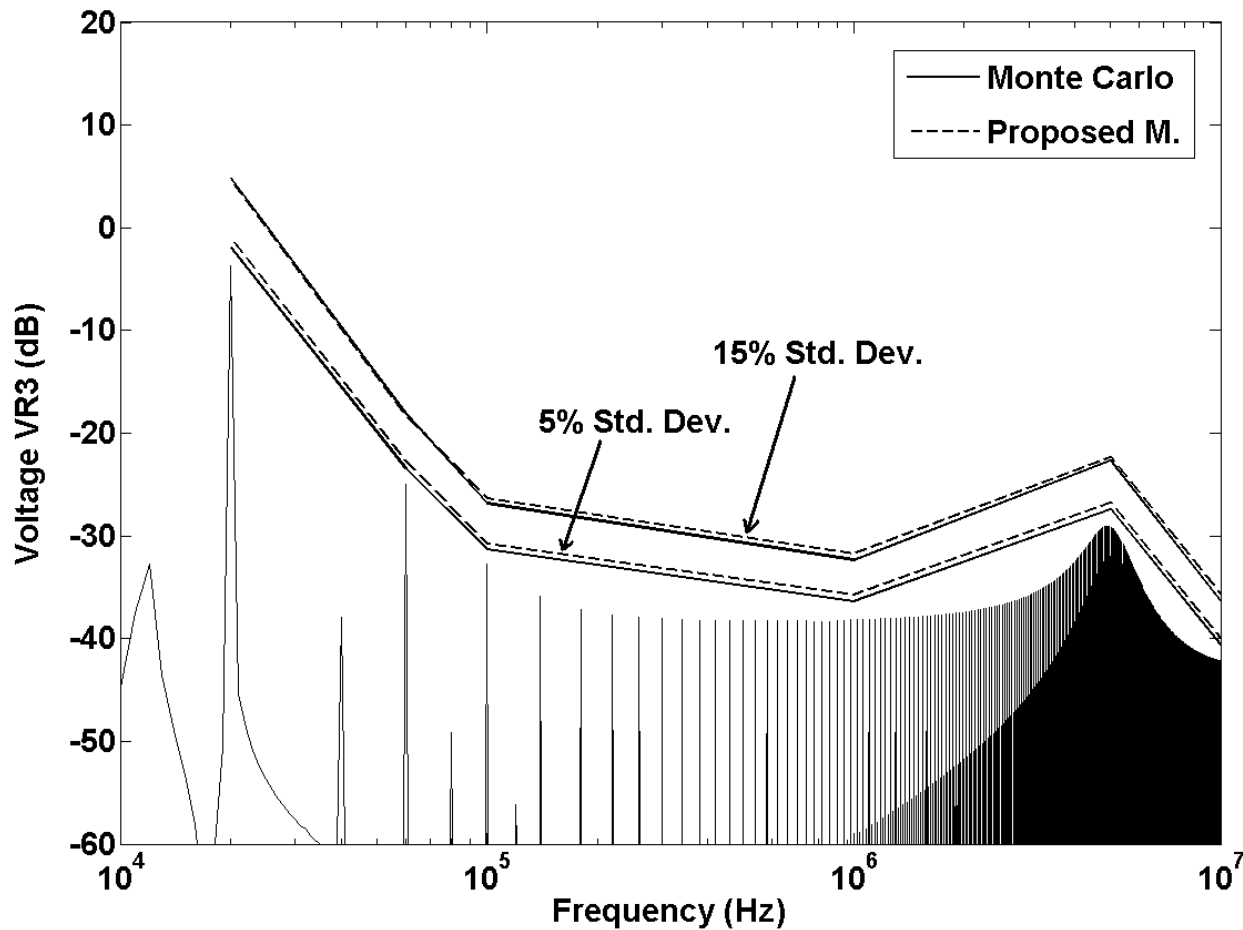
Results – Confidence Intervals

99.9%



Results – Confidence Intervals

99.9%



↪ **Polynomial Chaos**

(Drawback: not efficient for large N of variables)

↪ **Random Matrix Theory (Edelman 2005)**

↪ **Heaviside and Dirac Generalized Functions
(Shamilov 2006)**

- ↪ [1] <http://product-image.tradeindia.com/00381377/b/3/AC-To-DC-Power-Converter-Multi-Output.jpg>
- ↪ [2] Redl, R.; , "Power electronics and electromagnetic compatibility," Power Electronics Specialists Conference, 1996. PESC '96 Record., 27th Annual IEEE , vol.1, no., pp.15-21 vol.1, 23-27 Jun 1996.
- ↪ [3] <http://www.ets-lindgren.com/pdf/3810-2.pdf>
- ↪ [4] 1. R. A X. de Menezes et al., "Efficient computation of stochastic EM problems using unscented transforms", IET Sci. Meas. Technol., vol. 2(2), pp. 88-95, 2008.
- ↪ [5] 02_Probability_part3.PDF